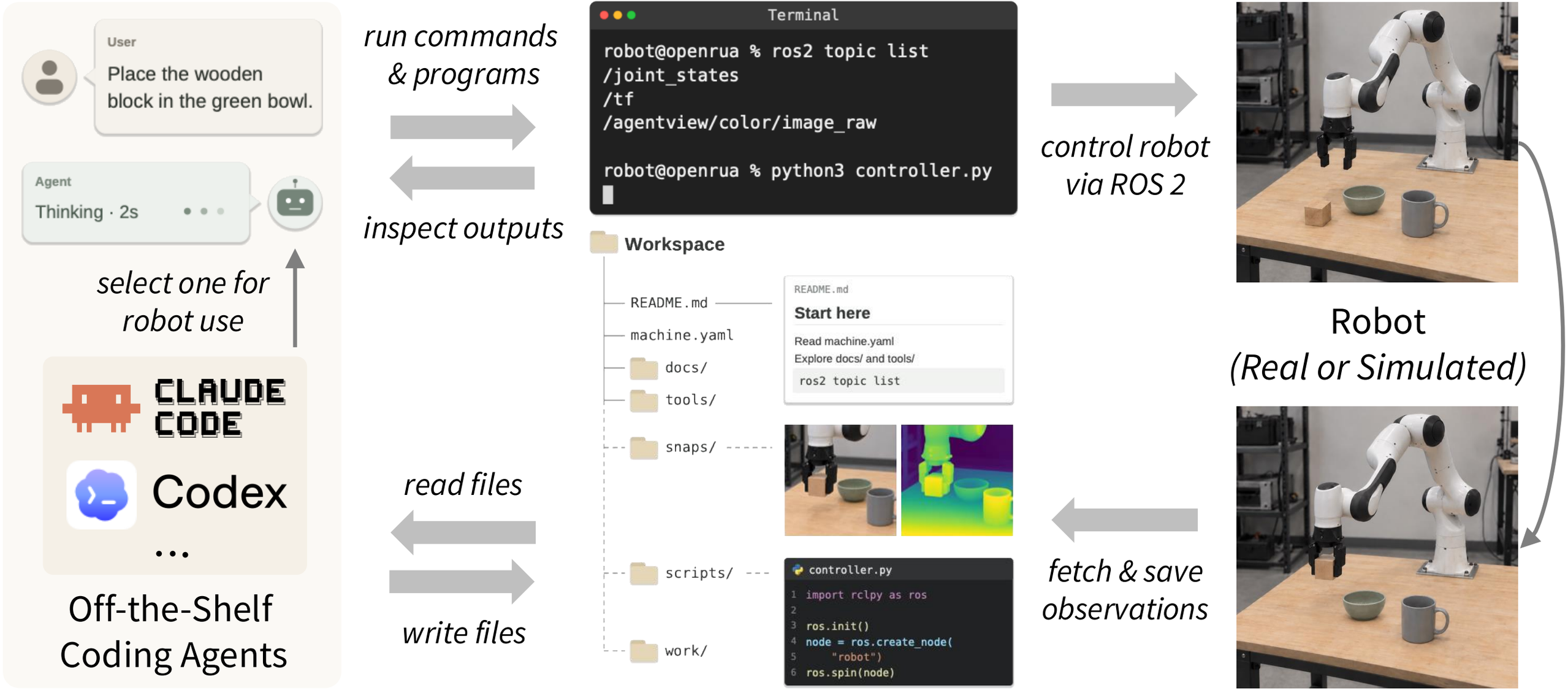

User
Place the wooden block in the green bowl.
Agent
Thinking · 2s
select one for robot use
CLAUDE CODE
Codex
...
Off-the-Shelf Coding Agents
run commands & programs
inspect outputs
read files
write files
Terminal
robot@openrua % ros2 topic list
/joint_states
/tf
/agentview/color/image_raw
robot@openrua % python3 controller.py
Workspace
README.md
machine.yaml
docs/
tools/
snaps/
scripts/
work/
README.md
Start here
Read machine.yaml
Explore docs/ and tools/
ros2 topic list
controller.py
import rclpy as ros
ros.init()
node = ros.create_node(
"robot")
ros.spin(node)
control robot via ROS 2
fetch & save observations
Robot
(Real or Simulated)